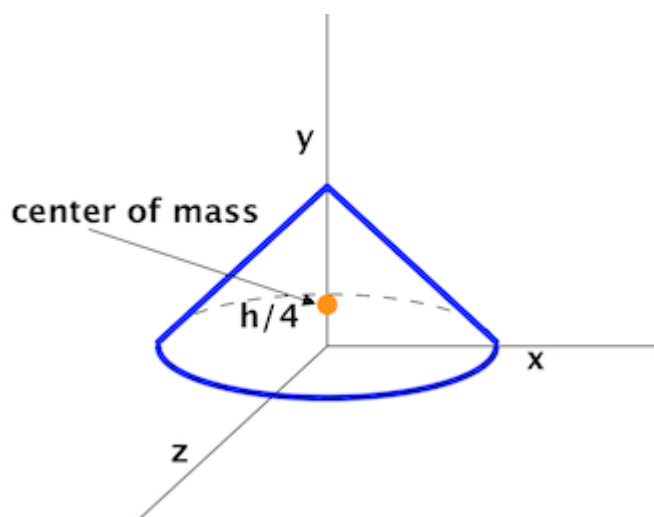
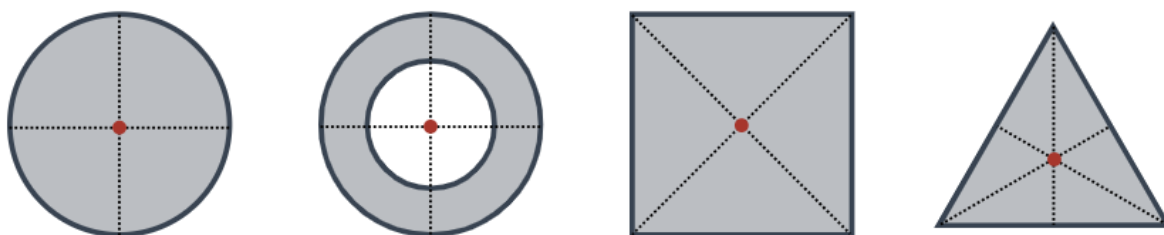


Harold's Center of Mass Cheat Sheet

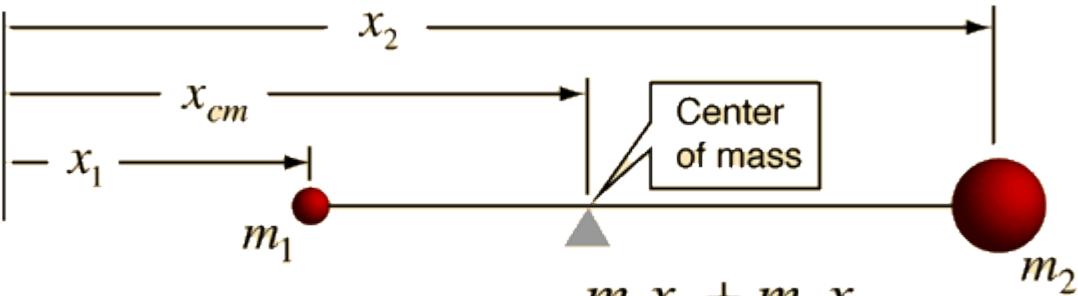
13 August 2020

Terms

Term	Description	Units
$\bar{x}$	Center of Mass along the x-axis. Same as x_{cm} .	<i>m or ft</i>
$\bar{y}$	Center of Mass along the y-axis.	<i>m or ft</i>
$\bar{z}$	Center of Mass along the z-axis.	<i>m or ft</i>
$\bar{x}$ $(\bar{x}, \bar{y})$ $(\bar{x}, \bar{y}, \bar{z})$	Center of Mass. The coordinates (point) where the object is perfectly balanced. (Centroid)	<i>m or ft</i>
M	Total mass. How heavy the object is. Is equal to it's area or volume if uniform density. (similar to Weight)	<i>kg or lb</i>
M_x and M_y	Moment. The line or axis on which the object can spin perfectly balanced.	<i>kg or lb</i>
M_x	Moment of Inertia about the x-axis	<i>kg or lb</i>
M_y	Moment of Inertia about the y-axis	<i>kg or lb</i>
I	Moment of Inertia, mass moment of Inertia, or rotational inertia of a body. I_0 = polar moment of inertia (about origin)	<i>kg m² or lb ft²</i>
ρ	Greek symbol rho for density or mass / volume or mass / area.	$\rho = \frac{kg}{m^3}$ or $\frac{lb}{ft^3}$
A	Area of lamina or plate	<i>m² or ft²</i>
V	Volume of a body or solid	<i>m³ or ft³</i>



Discrete

Term	1-D	2-D	3-D
$\bar{x}$	$\bar{x} = \frac{m_1 x_1 + m_2 x_2}{m_1 + m_2}$	$\bar{x} = \frac{M_y}{M}$	$\bar{x} = \frac{1}{M} \sum_{i=1}^N m_i x_i$
$\bar{y}$	NA	$\bar{y} = \frac{M_x}{M}$	$\bar{y} = \frac{1}{M} \sum_{i=1}^N m_i y_i$
$\bar{z}$	NA	NA	$\bar{z} = \frac{1}{M} \sum_{i=1}^N m_i z_i$
M	$M = \sum_{i=1}^N m_i$		
M_x	$M_x = \sum_{i=1}^N m_i y_i$		
M_y	$M_y = \sum_{i=1}^N m_i x_i$		
I	$I = m r^2 = \frac{L}{\omega}$	$I = \sum_{i=1}^N m_i r_i^2$	NA
I_x	$I_x = \sum_{i=1}^j x_i^2 \frac{M}{L} \Delta x$	$I_x = \sum_{i=1}^k \sum_{j=1}^l y^2 \rho(x, y) \Delta A$	$I_x = \sum_{i=1}^l \sum_{j=1}^m \sum_{k=1}^n (y^2 + z^2) \rho(x, y, z) \Delta V$
I_y	NA	$I_y = \sum_{i=1}^k \sum_{j=1}^l x^2 \rho(x, y) \Delta A$	$I_y = \text{Above with } (x^2 + z^2)$
I_z	NA	NA	$I_z = \text{Above with } (x^2 + y^2)$
I_0	$I_0 = I_x$	$I_0 = I_x + I_y$	$I_0 = I_x + I_y + I_z$
 For two masses: $x_{cm} = \frac{m_1 x_1 + m_2 x_2}{m_1 + m_2}$			

Continuous

Term	2-D	3-D
$\bar{x}$	$\bar{x} = \frac{M_y}{M}$	$\bar{x} = \frac{1}{M} \int_0^M x \, dm = \frac{M_{yz}}{M}$
$\bar{y}$	$\bar{y} = \frac{M_x}{M}$	$\bar{y} = \frac{1}{M} \int_0^M y \, dm = \frac{M_{xz}}{M}$
$\bar{z}$	NA	$\bar{z} = \frac{1}{M} \int_0^M z \, dm = \frac{M_{xy}}{M}$ $\bar{z} = \frac{1}{V} \int_{z_{\min}}^{z_{\max}} z \, dV$
M	$M = \rho (\text{Area})$ $M = \rho \int_a^b f(x) \, dx$ $M = \iint_R dm = \iint_R \rho(x, y) \, dA$ $dm = \rho(x, y) \, dy \, dx$	$M = \rho (\text{Volume})$ $M = \iiint_Q dm = \iiint_Q \rho(x, y, z) \, dV$ $dm = \rho(x, y, z) \, dz \, dy \, dx$
M_x	$M_x = \rho \iint_R y \, dA = \rho \int_a^b \frac{1}{2} ([f(x)]^2) \, dx$	$M_{xy} = \iiint_Q z \rho(x, y, z) \, dV$
M_y	$M_y = \rho \iint_R x \, dA = \rho \int_a^b x f(x) \, dx$	$M_{yz} = \iiint_Q x \rho(x, y, z) \, dV$
M_z	NA	$M_{xz} = \iiint_Q y \rho(x, y, z) \, dV$
I	$I = \int_0^a m r^2 \, dr$ $I = \iint_A \rho(r) d(r)^2 \, dA(r)$	$I = \iiint_V \rho(r) d(r)^2 \, dV(r)$
I_x	$I_x = \iint_R y^2 \rho(x, y) \, dA$	$I_x = \iiint_Q (y^2 + z^2) \rho(x, y, z) \, dV$
I_y	$I_y = \iint_R x^2 \rho(x, y) \, dA$	$I_y = \iiint_Q (x^2 + z^2) \rho(x, y, z) \, dV$
I_z	NA	$I_z = \iiint_Q (x^2 + y^2) \rho(x, y, z) \, dV$
$x_{cm} = \frac{\int_0^L x \frac{M}{L} \, dx}{M} = \frac{1}{L} \frac{x^2}{2} \Big _{x=0}^{x=L} = \frac{L}{2}$		